Consecutive-type Reliability Structures Under Warm Standby Redundancy: Some Advances

Ioannis S. Triantafyllou

Department of Statistics and Insurance Science, University of Piraeus, Greece E-mail: itriantafyllou@unipi.gr

Received 14 September 2024; Accepted 04 October 2024

Abstract

In the present article, we investigate two different reliability structures, which belong to the class of consecutive-type systems under redundancy policy. The resulting structures consist of n independent components, but they also dispose warm standby ones. The distribution of the number of working warm components at the time of system's failure is studied in some detail. Among others, explicit expressions for determining the corresponding probability mass function are established. A short discussion for future work is also developed.

Keywords: 2-within-consecutive-k-out-of-n structures, $(n, f, 2)$ systems, warm standby redundancy, Samaniego's signature.

1 Introduction

In the last four decades, the class of consecutive-type systems has been enormously developed. The fundamental member of this family is the socalled consecutive-k-out-of-n: F system $(1 \leq k \leq n)$, which consists of n components and fails if and only if at least k consecutive ones fail

Journal of Graphic Era University, Vol. 12 2, 297–308. doi: 10.13052/jgeu0975-1416.1227 © 2024 River Publishers

(see, e.g. [1–4]). It is evident that several extensions of the aforementioned structure have been introduced and studied in the literature. For instance, the r-within-consecutive-k-out-of-n system is a natural generalization of the consecutive-k-out-of-n: F model and fails if and only if at least r out of consecutive k components fail $(1 \leq r \leq k)$. It is straightforward that for $r = k$, the r-within-consecutive-k-out-of-n system reduces to a consecutive-k-out-of-n system (see, e.g. $[5, 6]$).

In addition, several reliability structures having two common failure criteria appear in the literature. Some of them include a consecutive-type failure criterion. For example, one may consider the well-known (n, f, k) structure, which consists of n components and fails if and only if at least f components or consecutive k components fail $(1 \leq k < f)$. It goes without saying that if $f \leq k$, the (n, f, k) system coincides to the traditional f-out-of-n: F model (see, e.g. [7–9]). Moreover, additional reliability systems with two (or more) failure criteria can be found in [10], wherein the so-called (n, f, k) model is introduced. The particular structure contains n components and fails if, and only if, there exist at least f failed components and at least k consecutive failed ones (see, also [11]). Among others, an alternative reliability model, whom operation is related to two different conditions, has been established in [12] and it combines a m-consecutive k-out-of-n: F and a consecutive k_c -out-of-n: F system.

Throughout the lines of the present work, we apply the well-known warm standby redundancy to two specific members of the class of consecutivetype systems. More precisely, we carry out a signature-based investigation for the 2-within-consecutive-k-out-of-n and the $(n, f, 2)$ system under the aforementioned redundancy policy. In Section 2, we present the definitions of key concepts that will be used later, the reliability models that will be explored, while the necessary terminology is also provided. Section 3 displays the main results of the paper, wherein closed formulae for the probability mass function of the number of working warm components at the time of system's failure are proved. Finally, Section 5 highlights the contribution of the present manuscript, while some thoughts for its extensions and/or generalizations are also provided.

2 The General Framework and Some Basic Concepts

Let us consider a reliability structure consisting of n_1 active components. We next denote by $T_1, T_2, \ldots, T_{n_1}$ the lifetimes of these components, while T corresponds to the system's lifetime. If we assume that $T_1, T_2, \ldots, T_{n_1}$ are

independent and identically distributed (*i.i.d.*, hereafter), the signature of the system is defined as the probability vector $(s_1(n), s_2(n), \ldots, s_{n_1}(n_1))$ with

$$
s_i = P(T = T_{i:n_1}), i = 1, 2, \dots, n_1,
$$
\n(1)

where $T_{1:n_1} \leq T_{2:n_1} \leq \cdots \leq T_{n_1:n_1}$ denote the respective order statistics of the random sample $T_1, T_2, \ldots, T_{n_1}$ (see, e.g. [13]). It is also known that the reliability function of any coherent system consisting of *i.i.d.* components can be determined by the aid of its signature as given below

$$
P(T > t) = \sum_{i=1}^{n_1} s_i P(T_{i:n_1} > t).
$$
 (2)

Based on [\(2\)](#page-2-0), one may readily conclude that the system's reliability function is a mixture of the reliability functions of the corresponding order statistics, with the mixture coefficients being the coefficients in the signature vector. In addition, it is quite interesting that this representation has been extended to the case of coherent systems with possibly dependent component lifetimes (see, e.g. [14]).

On the other hand, the enhancement of the performance of the underlying reliability structures can be gained by applying a standby redundancy therein. Among other types, we next consider the so-called warm standby redundancy (see, e.g. [15]). That practically means that we assume that n_2 inactive (warm) components are available for the system, and they can be used whenever it is needed. It is evident that reliability structures under warm redundancy fit well to several real-life applications. For instance, one may consider the so-called cloud computing, wherein load balancers are used to distribute incoming traffic across multiple servers. A warm redundancy policy can be applied to backup load balancers, where a secondary load balancer remains in a standby mode. Another real-life example refers to air traffic control systems, which should maintain high availability for flight safety. Warm redundancy can be used for radar or communication systems where a backup system stays partially active, constantly receiving updates from the active system. For instance, an optimization approach for warm standby series-parallel systems is provided by [16]. Moreover, the reliability of multi-state systems that incorporate warm standby components is investigated by [17]. For a detailed study on the warm redundancy policy, the interested reader is referred to [18].

Under such a scenario, the failure rate of the warm components is assumed to be smaller than the corresponding rate of the active components of the underlying structure. Therefore, some warm components are expected

Figure 1 Failure scenarios for the 2-within-consecutive-3-out-of-6 system.

to have failed at the time of system's failure. However, some of them are supposed to work at the same time. If we denote by $W_1, W_2, \ldots, W_{n_2}$ the random lifetimes of the inactive warm components of the coherent system, we expect that some of these random variables shall take on larger values with larger probability than the corresponding lifetimes of the active components.

Throughout the lines of the present manuscript, we investigate two different members of the class of consecutive-type systems under warm redundancy policy. The first one is known as r -within-consecutive- k -out-of n systems and fails if and only if at least r out of consecutive k components fail $(1 \le r \le k)$. For instance, if we consider the special case $n = 6, r = 2$, $k = 3$, the resulting structure of order 6 fails if and only if there exist at least 2 failed components among 3 consecutive ones. For the particular structure, all failure scenarios having a total number of 3 failed components are presented at Figure [1,](#page-3-0) where \bullet (\circ) corresponds to a failed (working) component.

Based on the first two scenarios appeared in Figure [1,](#page-3-0) we readily observe that the underlying reliability structure fails if components lying at the first three consecutive positions fail or the first two components and the forth component stop their operation.

In the sequel, we shall also consider the so-called (n, f, k) structure, which is a reliability model with two common failure criteria. More precisely, the particular system consists of n components and fails if and only at least f

Figure 2 Failure scenarios for the $(6, 3, 2)$ system.

components or at least consecutive k components fail $(1 \leq k < f)$. Figure [2](#page-4-0) illustrates all combinations of working and failed components, which lead to the failure of a $(6, 3, 2)$ system.

Based on the first two scenarios appeared in Figure [2,](#page-4-0) we readily observe that the underlying reliability structure fails if components lying at the first two consecutive positions fail or the second and the third component stop their operation.

3 Main Results

In the present section, we establish the main results of the article referring to structures under redundancy. We next consider a coherent system consisting of n_1 components and n_2 warm (inactive) ones. Our target is to investigate the number of warm components, which are still working at the time of system's breakdown.

Let us first denote by $T_1, T_2, \ldots, T_{n_1}$ the lifetimes of the active components of the structure, while $W_1, W_2, \ldots, W_{n_2}$ correspond to the random lifetimes of the available warm (inactive) components. If T represents the lifetime of the system, we next define the random variable W such as

$$
W = \sum_{i=1}^{n_2} I(W_i > T),
$$
\n(3)

which corresponds to the number of surviving warm components at the time point of system's failure. Kindly note that the random variable $I(W_i > T)$, which appears in [\(3\)](#page-4-1), provides the information whether the i −th warm component is still working $(I(W_i > T) = 1)$ or not $(I(W_i > T) = 0)$.

The following proposition offers explicit expressions for determining the probability mass function of the variable W defined earlier, within a 2-withinconsecutive- k -out-of- n_1 system consisting of *i.i.d.* components.

Proposition 1. Let us consider a 2-within-consecutive- k -out-of- n_1 system under warm standby redundancy. If we denote by n_2 the number of its warm components and by W the number of surviving warm components at the time point of system's failure ($W \le n_2$), then if the lifetimes of both active and warm components are *i.i.d.* and exponentially distributed with parameters λ_1 and λ_2 respectively, the probability mass function of random variable W can be determined as

$$
P(W = w) = {n_2 \choose w} \sum_{i=1}^{n_1} \lambda_1^i \left((n_1 - i + 1) {n_1 - (k-1)(i-2) \choose i-1} - i {n_1 - (k-1)(i-1) \choose i} \right)
$$

$$
\times \int_0^\infty e^{-(w\lambda_2 - \lambda_1)t} t^i (1 - e^{-\lambda_2 t})^{n_2 - w} (1 - e^{-\lambda_1 t})^{n_1 - i} dt.
$$
 (4)

Proof. The lifetimes $T_1, T_2, \ldots, T_{n_1}$ of the active components of the underlying 2-within-consecutive- k -out-of- n_1 system is assumed to follow Exponential distribution with parameter λ_1 . Therefore, we may express their common survival function as

$$
P(T_i > t) = \overline{F}(t) = 1 - F(t) = e^{-\lambda_1 t}, t > 0, \quad i = 1, 2, \dots, n_1.
$$
 (5)

In a similar manner, one may easily conclude that, since the warm components are assumed to follow an Exponential distribution with parameter λ_2 , their common survival function is determined as

$$
P(W_i > t) = \overline{G}(t) = 1 - G(t) = e^{-\lambda_2 t}, t > 0, \quad i = 1, 2, \dots, n_2.
$$
 (6)

By definition, the variable W takes on value w , if exactly w warm components out of the n_2 available ones have survived till the overall failure of the underlying structure $(0 \leq w \leq n_2)$. In simpler words, the event ${W = w}$ coincides to the event {*exactly w W_i's are greater than T*}. Since the components are assumed to be independent and identically distributed,

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we readily observe that

$$
P(W = w) = {n_2 \choose w} P(W_1 > T, W_2 > T, \dots, W_w > T,
$$

$$
W_{w+1} \leq T, W_{w+2} \leq T, \dots, W_{n_2} \leq T),
$$
 (7)

where

$$
\binom{n_2}{w} = \frac{n_2}{w!(n_2 - w)!} \tag{8}
$$

corresponds to the number of ways to pick w objects out of n_2 ones. We next condition the above expression on T and by recalling the independence between the warm components the following result is straightforward

$$
P(W = w) = {n_2 \choose w} \int_0^\infty \prod_{i=1}^w P(W_i > t) \prod_{i=1}^{n_2 - w} P(W_i \le t) dP(T \le t). \tag{9}
$$

Substituting [\(6\)](#page-5-0) in [\(9\)](#page-6-0), we obtain that

$$
P(W = w) = {n_2 \choose w} \int_0^\infty \prod_{i=1}^w e^{-\lambda_2 t} \prod_{i=1}^{n_2 - w} (1 - e^{-\lambda_2 t}) dP(T \le t)
$$

or equivalently

$$
P(W = w) = {n_2 \choose w} \int_0^{\infty} e^{-w\lambda_2 t} (1 - e^{-\lambda_2 t})^{n_2 - w} dP(T \le t).
$$
 (10)

By the aid of [\(2\)](#page-2-0), the latter expression takes on the following form

$$
P(W = w) = {n_2 \choose w} \sum_{i=1}^{n_1} s_i^{2:k} \int_0^\infty e^{-w\lambda_2 t} (1 - e^{-\lambda_2 t})^{n_2 - w} f_{i:n_1}(t) dt,
$$
\n(11)

where $s_i^{2:k}$ denotes the $i-th$ coordinate of the signature vector of the 2-within-consecutive-k-out-of- n_1 system, while $f_{i:n_1}$ corresponds to the probability density function of the $i-th$ order statistic $T_{i:n_1}$. Recalling the well-known formula (see, e.g. [19])

$$
f_{i:n_1}(t) = \frac{n_1!}{(i-1)!(n_1-i)!} \lambda_1 (\lambda_1 t)^{i-1} e^{-\lambda_1 t} (1 - e^{-\lambda_1 t})^{n_1-i}, \qquad (12)
$$

we may rewrite [\(11\)](#page-6-1) as

$$
P(W = w) = {n_2 \choose w} \sum_{i=1}^{n_1} s_i^{2:k} {n_1 \choose i} \int_0^\infty e^{-(w\lambda_2 - \lambda_1)t} i\lambda_1 (\lambda_1 t)^{i-1}
$$

$$
\times (1 - e^{-\lambda_2 t})^{n_2 - w} (1 - e^{-\lambda_1 t})^{n_1 - i} dt.
$$
 (13)

However, the coordinates of the signature vector for a 2-withinconsecutive-k-out-of- n_1 system can be determined by the aid of the following expression (see, e.g. [5])

$$
s_i^{2:k} = \frac{(n_1 - i + 1)\binom{n_1 - (k-1)(i-2)}{i-1} - i\binom{n_1 - (k-1)(i-1)}{i}}{i\binom{n_1}{i}}, \quad i = 1, 2, \dots, n_1
$$
\n(14)

We next combine formulae [\(13\)](#page-7-0) and [\(14\)](#page-7-1) and the desired result is straightforward.

Proposition 2 provides closed formulae for determining the probability mass function of the variable W defined in [\(3\)](#page-4-1), within a $(n_1, f, 2)$ system consisting of *i.i.d.* components.

Proposition 2. Let us consider a $(n_1, f, 2)$ system under warm standby redundancy. If we denote by n_2 the number of its warm components and by W the number of surviving warm components at the time point of system's failure $(W \le n_2)$, then if the lifetimes of both active and warm components are *i.i.d.* and exponentially distributed with parameters λ_1 and λ_2 respectively, then the probability mass function of random variable W can be determined as

$$
P(W = w) = {n_2 \choose w} \left(\sum_{i=1}^{f-1} \lambda_1^i \left((n-i+1) {n-i+2 \choose i-1} - j {n-i+1 \choose i} \right) \right)
$$

$$
+ i {n_1 \choose i} \lambda_1^f \sum_{j=f}^n \frac{(n-j+1) {n-j+2 \choose j-1} - j {n-j+1 \choose j}}{j {n \choose j}}
$$

$$
\times \int_0^\infty e^{-(w\lambda_2 - \lambda_1)t} t^i (1 - e^{-\lambda_2 t})^{n_2 - w} (1 - e^{-\lambda_1 t})^{n_1 - i} dt.
$$
(15)

Proof. The lifetimes $T_1, T_2, \ldots, T_{n_1}$ of the active components of the underlying $(n_1, f, 2)$ system is assumed to follow Exponential distribution with parameter λ_1 . Therefore, their common survival function can be determined by the aid of [\(5\)](#page-5-1). In addition, the warm components are assumed to follow an Exponential distribution with parameter λ_2 . Therefore, their common survival function can be expressed via [\(6\)](#page-5-0).

As mentioned earlier, the variable W takes on value w , if exactly w warm components out of the n_2 available ones have survived till the overall failure of the underlying structure $(0 \leq w \leq n_2)$. Based on the fact that the components are assumed to be independent and identically distributed, we once again conclude that $P(W = w)$ for the $(n_1, f, 2)$ system can be computed by the aid of [\(10\)](#page-6-2).

We next combine [\(2\)](#page-2-0) and [\(10\)](#page-6-2) and the following holds true

$$
P(W = w) = {n_2 \choose w} \sum_{i=1}^{n_1} s_i^{n,f,2} \int_0^\infty e^{-w\lambda_2 t} (1 - e^{-\lambda_2 t})^{n_2 - w} f_{i:n_1}(t) dt,
$$
\n(16)

where $s_i^{n,f,2}$ $i^{n,j,2}$ denotes the $i - th$ coordinate of the signature vector of the $(n_1, f, 2)$ system, while the probability density function of the $i - th$ order statistic $T_{i:n_1}$, e.g. $f_{i:n_1}$ is given by [\(12\)](#page-6-3). Substituting (12) in [\(16\)](#page-8-0) we observe that

$$
P(W = w) = {n_2 \choose w} \sum_{i=1}^{n_1} s_i^{n,f,2} {n_1 \choose i} \int_0^{\infty} e^{-(w\lambda_2 - \lambda_1)t} i\lambda_1^{i} t^{i-1}
$$

$$
\times (1 - e^{-\lambda_2 t})^{n_2 - w} (1 - e^{-\lambda_1 t})^{n_1 - i} dt.
$$
 (17)

However, the coordinates of the signature vector for a $(n_1, f, 2)$ system can be determined by the aid of the following expression (see, e.g. [20])

$$
s_i^{n,f,2} = \begin{cases} \frac{(n-i+1)\binom{n-i+2}{i-1} - j\binom{n-i+1}{i}}{i\binom{n}{i}}, & i = 1, 2, \dots, f-1\\ \sum_{j=f}^{n} \frac{(n-j+1)\binom{n-j+2}{j-1} - j n - j + 1 j}{j\binom{n}{j}}, & i = f\\ 0, & i = f+1, \\ 0, & f+2, \dots, n \end{cases}
$$
(18)

We next combine formulae [\(17\)](#page-8-1) and [\(18\)](#page-8-2) and the desired result is readily derived. ■

4 Discussion

In the present work, a signature-based analysis of coherent structures under warm redundancy has been carried out. General speaking, warm redundancy can be particularly useful in systems that require a balance between high availability and cost-effectiveness. Among others, a key reason why warm redundancy proves valuable is that warm redundancy ensures a backup system which can quickly take over in case of a primary system failure, minimizing service interruptions. The theoretical results have been produced under independence. Explicit formulae for determining the probability mass function of the number of alive warm components at the system's failure are delivered for specific consecutive-type structures. The main contribution of the present work is the investigation of the particular consecutive-type systems under redundancy and the establishment of closed expressions for evaluating their performance. It could be interesting to investigate different reliability structures under warm redundancy and/or having an alternative type of redundancy policy.

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Biography

Ioannis S. Triantafyllou received the bachelor's degree in Mathematics from National and Kapodistrian University of Athens in 2002, the master's degree in Applied Statistics from University of Piraeus in 2005, and the philosophy of doctorate degree in Probability & Statistics from University of Piraeus in 2009, respectively. He is currently working as an Assistant Professor at the Department of Statistics & Insurance Science, University of Piraeus. His research interests include Applied Probability, Reliability Theory, Nonparametric Statistics and Statistical Process Control. He has been serving as a reviewer for many highly-respected journals.